

Ergodic convergence results for the Arrow–Hurwicz differential system

Simon K. Niederländer

Autonomous Systems and Control
Siemens Technology

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Problem statement

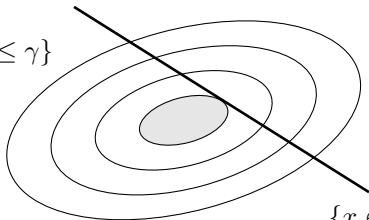
Let X, Y be real Hilbert spaces endowed with inner products $\langle \cdot, \cdot \rangle_X$, $\langle \cdot, \cdot \rangle_Y$ and induced norms $\|\cdot\|_X$, $\|\cdot\|_Y$.

Problem. Consider the minimization problem

$$\text{minimize } f(x) \quad \text{subject to } h(x) = 0_Y. \quad (\text{P})$$

- $f : X \rightarrow \mathbb{R}$ is convex and continuously differentiable
- $h : X \rightarrow Y$ is continuous and affine

$$\{x \in X \mid f(x) \leq \gamma\}$$



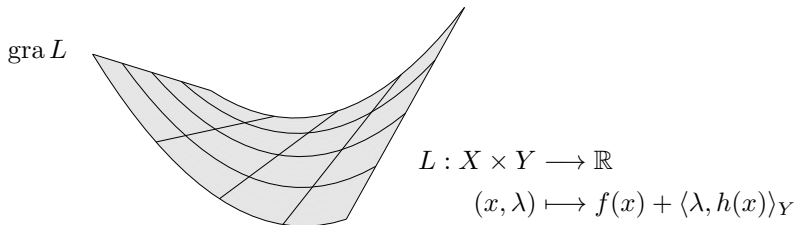
$$\{x \in X \mid h(x) = 0_Y\}$$

The Arrow–Hurwicz differential system

Arrow–Hurwicz differential system. We reconsider the classical first-order evolution system¹

$$\begin{cases} \dot{x} + \nabla f(x) + h'(x)^* \lambda = 0_X \\ \dot{\lambda} - h(x) = 0_Y \end{cases} \quad (\text{AH})$$

in view of solving the convex minimization problem (P).



¹K. J. Arrow and L. Hurwicz, *A gradient method for approximating saddle points and constrained maxima*, RAND Corp., Santa Monica, CA, pp. p-223, 1951.

Outline

Introduction

Basic properties

(Maximal) monotonicity, integrability estimate, ...

Weak ergodic convergence

Limiting average behavior, localization of the weak limit, ...

Refined ergodic estimates

"Primal-dual gap function", refined asymptotics, ...

Further extension

Liénard-type inertial dynamics, ...

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Preliminaries

Let us associate with (P) the *Lagrangian*

$$\begin{aligned} L : X \times Y &\longrightarrow \mathbb{R} \\ (x, \lambda) &\longmapsto f(x) + \langle \lambda, h(x) \rangle_Y. \end{aligned}$$

Definition. A pair $(\bar{x}, \bar{\lambda}) \in X \times Y$ is a *saddle point* of L if

$$L(\bar{x}, \lambda) \leq L(\bar{x}, \bar{\lambda}) \leq L(x, \bar{\lambda}) \quad \forall (x, \lambda) \in X \times Y.$$

We denote by $S \times M \subset X \times Y$ the set of saddle points of L .

Assumptions.

- $f : X \rightarrow \mathbb{R}$ is convex and continuously differentiable
- $\nabla f : X \rightarrow X$ is Lipschitz continuous on bounded sets
- $A : X \rightarrow Y$ is linear and continuous, $b \in Y$, and

$$\begin{aligned} h : X &\longrightarrow Y \\ x &\longmapsto Ax - b \end{aligned}$$

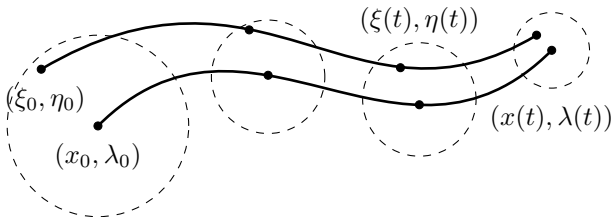
(Maximal) monotonicity

Given our basic assumptions, we have the following important property concerning the (AH) differential system:

Main feature. *(Maximal) monotonicity* of the “(AH) generator”²

$$T : X \times Y \longrightarrow X \times Y$$

$$(x, \lambda) \longmapsto (\nabla f(x) + A^* \lambda, b - Ax).$$



²R. T. Rockafellar, *Monotone operators associated with saddle-functions and mini-max problems*, in Nonlinear Functional Analysis, Amer. Math. Soc., pp. 241-250, 1969.

Integrability estimate

Consider the “primal-dual gap function” (relative to $S \times M$)

$$t \longmapsto L(x(t), \cdot) - L(\cdot, \lambda(t))$$

as a natural measure of optimality.

Proposition. Let $S \times M$ be non-empty and let $(x, \lambda) : [0, +\infty) \rightarrow X \times Y$ be a solution of (AH). Then, for any $(\xi, \eta) \in S \times M$, it holds that

$$\int_0^\infty L(x(\tau), \eta) - L(\xi, \lambda(\tau)) \, d\tau < +\infty.$$

Define the *Cesàro average* of a solution (x, λ) of (AH) as

$$\begin{aligned} (\sigma, \omega) : (0, +\infty) &\longrightarrow X \times Y \\ t &\longmapsto \frac{1}{t} \int_0^t (x(\tau), \lambda(\tau)) \, d\tau. \end{aligned}$$

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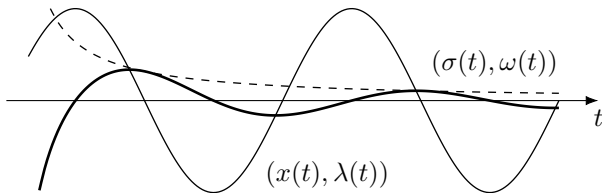
Weak ergodic convergence

Theorem. Let $S \times M$ be non-empty and let $(\sigma, \omega) : (0, +\infty) \rightarrow X \times Y$ be the Cesàro average of a solution of (AH). Then, for any $(\xi, \eta) \in S \times M$, it holds that

$$L(\sigma(t), \eta) - L(\xi, \omega(t)) = \mathcal{O}\left(\frac{1}{t}\right) \text{ as } t \rightarrow +\infty.$$

Moreover, there exists $(\bar{\sigma}, \bar{\omega}) \in S \times M$ such that $(\sigma(t), \omega(t)) \rightharpoonup (\bar{\sigma}, \bar{\omega})$ weakly in $X \times Y$ as $t \rightarrow +\infty$.

Corollary. If $S \times M$ is empty, then $\lim_{t \rightarrow +\infty} \|(\sigma(t), \omega(t))\| = +\infty$.



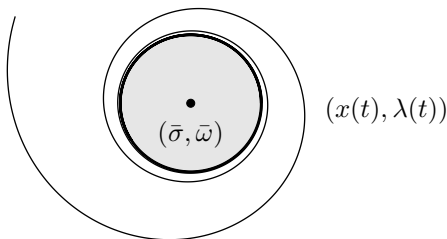
Localization of the weak limit

Given a *bounded* solution (x, λ) of (AH), consider³

$$\phi(\xi, \eta) = \limsup_{t \rightarrow +\infty} \|(x(t), \lambda(t)) - (\xi, \eta)\|^2.$$

Proposition. Let $S \times M$ be non-empty and let $(\bar{\sigma}, \bar{\omega}) \in S \times M$ be such that $(\sigma(t), \omega(t)) \rightharpoonup (\bar{\sigma}, \bar{\omega})$ weakly in $X \times Y$ as $t \rightarrow +\infty$. Then,

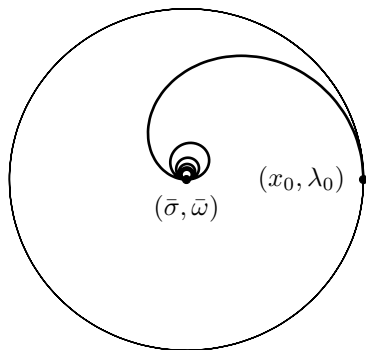
$$\phi(\bar{\sigma}, \bar{\omega}) \leq \phi(\xi, \eta) \quad \forall (\xi, \eta) \in X \times Y.$$



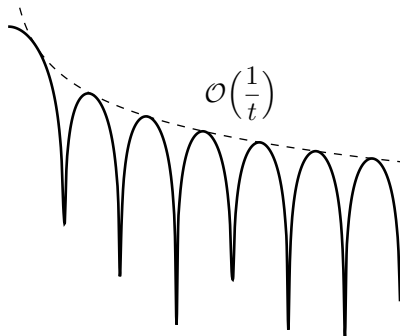
³M. Edelstein, *The construction of an asymptotic center with a fixed-point property*, Bull. Amer. Math. Soc., 78:206-208, 1972.

Numerical experiment

Illustration.



$$\{(\sigma(t), \omega(t)) \mid t > 0\}$$



$$\|(\sigma(t), \omega(t)) - (\bar{\sigma}, \bar{\omega})\|$$

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Refined ergodic estimates

Let us assume that $A : X \rightarrow Y$ is bounded from below, i.e.,

$$\exists \beta > 0 \quad \forall x \in X, \quad \|Ax\|_Y \geq \beta \|x\|_X.$$

Proposition. Let $S \times M$ be non-empty, let $A : X \rightarrow Y$ be bounded from below, and let $(\sigma, \omega) : (0, +\infty) \rightarrow X \times Y$ be the Cesàro average of a solution of (AH). Then, for any $(\xi, \eta) \in S \times M$, it holds that

$$L(\sigma(t), \eta) - L(\xi, \omega(t)) = \mathcal{O}\left(\frac{1}{t^2}\right) \text{ as } t \rightarrow +\infty;$$

$$\|\sigma(t) - \xi\|_X = \mathcal{O}\left(\frac{1}{t}\right) \text{ as } t \rightarrow +\infty.$$

Implication.

$$S \times M = \left\{ \bullet \right\} \times \left\{ \text{parallelogram} \right\}$$

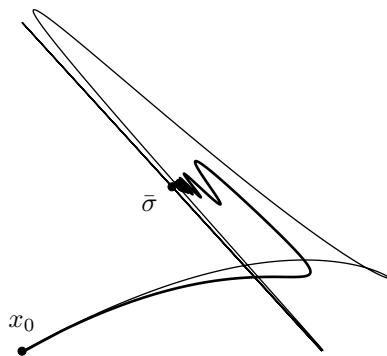
• ... unique minimizer of (P)



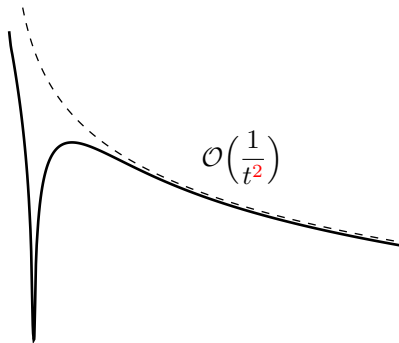
... affine subspace of Lagrange multipliers

Numerical experiment

Illustration.



$$\{\sigma(t) \mid t > 0\}$$



$$L(\sigma(t), \bar{\omega}) - L(\bar{\sigma}, \omega(t))$$

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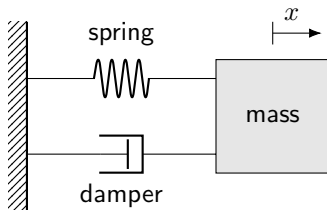
A Liénard-type differential system

The Arrow–Hurwicz differential system (AH) admits an equivalent second-order representation in terms of the

Liénard-type inertial dynamics. Consider the second-order evolution system⁴

$$\ddot{x} + \nabla^2 f(x) \dot{x} + \nabla \|h(x)\|_Y^2 / 2 = 0_X \quad (\text{ID})$$

relative to the convex minimization problem (P).



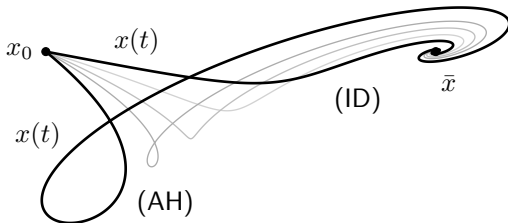
⁴A. Liénard, *Étude des oscillations entretenues*, Rev. gén. d'électr., 23:901-912 and 946-954, 1928.

Link between the dynamics

We have the following relation between the Arrow–Hurwicz differential system (AH) and the Liénard-type inertial dynamics (ID):

Connection.

$$\begin{array}{ccc}
 & \xrightarrow{f \in \mathcal{C}^2} & \\
 \left\{ \begin{array}{l} \dot{x} + \nabla f(x) + h'(x)^* \lambda = 0_X \\ \dot{\lambda} - h(x) = 0_Y \end{array} \right. & \quad \quad & \ddot{x} + \nabla^2 f(x) \dot{x} + \nabla \|h(x)\|_Y^2 / 2 = 0_X \\
 & \xleftarrow{h'(\cdot) \text{ surjective}} &
 \end{array}$$



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Thank you for your attention!

